

BASIC INSTRUCTION IDX-PRO-RT ROLLTEK

CONFIGURATION BY REMOTE

INITIAL CONFIGURATION BY REMOTE

1st REMOTE CONTROL ASSOCIATION

- 1. Hold down on **motor head switch P2** (Green Label) until <u>motor jogs once</u>.
- Press and release **UP** button on remote control, <u>motor will jog once</u>.
 ✓ Remote association is done.

UP LIMIT, DOWN LIMIT AND TILT POSITION ADJUSTMENT

 Λ If motor direction is not correct, it needs to be changed before continuing with initial configuration. Λ

- 1. Hold down on **motor head switch P1** (Red Label) until <u>motor jogs once</u>.
 - ✓ Rotation direction it's changed.
 - 1. On remote control, press and release P3 (rear hidden switch). Motor will jog once.
 - 2. Move the blind to **upper** position and press **P3** on remote control. Motor will jog once.
 - 3. Move blind to **lower** position and press **P3** on remote. Motor will jog once.
 - Move blind to tilt position and press P3 on remote. Motor will jog once.
 ✓ Limit switches are set.

POSITION CORRECTION BY REMOTE

- 1. Move blind to limit will be adjusted
- 2. On remote control, press and release **P3** (rear hidden switch). Motor will jog once.
- 3. Move blind to new position, press and release **P3** switch. <u>Motor will jog once.</u>
 ✓ Readjustment is done.

2on REMOTE ASSOCIATION (Max. 7)

- 1. Move blind to an intermediate position (NO Upper, Lower or Tilt position).
- 2. Press and maintain **P3** on associated remote control, until motor joas once.
- 3. Press and release **UP** on remote to be associated. <u>Motor will jog once</u>.

 ✓ Remote association it's done.

DELETE ASSOCIATED REMOTE CONTROL BY REMOTE

- 1. Move blind to an intermediate position (NO Upper, Lower or Tilt position).
- 2. Press and maintain **P3** on associated remote control, until motor jogs once.
- 3. Press and release **P3** on remote to be deleted. Motor will <u>jog once</u>.
 ✓ Remote delete it's done.



CONFIGURATION BY WALL SWITCH

WALL SWITCH BUTTONS USE

Same functions in standard and configuration mode:

- Press Up or Down once: **UP or DOWN one step.**
- Press Up or Down for 2 sec: UP or DOWN movement in continuous.
- Press Up or Down while moving: STOP.

In configuration mode:

• Hold Up + Down: action confirmation, motor will jog once.

In standard mode:

• Hold Up + Down: motor moves to tilting position.

INITIAL CONFIGURATION THROUGH WALL SWITCH

UP LIMIT, DOWN LIMIT AND TILT POSITION ADJUSTMENT BY WALL SWITCH

⚠ If motor direction is not correct, it needs to be changed before continuing with initial configuration. ⚠

- t **motor direction is not correct, it needs to be changed before continuing with initial contiguration.** *L*1 2. Hold down on **motor head switch P1** (Red Label) until motor jogs once.
- ✓ Rotation direction it's changed.
- 1. Hold **UP + DOWN** switch for 2 sec. Motor will jog once.
- 2. Move blind to upper position and press UP + DOWN switch for 2 sec. Motor will jog once.
- 3. Move blind to **lower** position and press **UP + DOWN** switch for 2 sec. <u>Motor will jog once</u>.
- 4. Move blind to **tilt** position and press **UP + DOWN** switch for 2 sec. <u>Motor will jog once</u>. ✓ Limit switches are set, and wall switch is now working in standard mode.

ALL POSITIONS READJUSTMENT THROUGH WALL SWITCH

- 1. Move blind to upper limit.
- 2. Hold **UP** switch until motor jogs two times.
- 3. Repeat "Initial configuration by wall switch" (points 2 to 4).

New positions will be stored in memory at the end of the adjustment process. If process is not finished and no action is detected during 60 sec, memory will return to default positions stored automatically.

REMOTE CONTROL ASSOCIATION THROUGH WALL SWITCH

- 1. Move blind to upper limit
- 2. Hold **UP** switch until motor jogs once.
- 3. Press and release **UP** button on remote control, <u>motor will jog once</u>.
 - ✓ Remote association it's done.

DELETE ALL ASSOCIATED REMOTE COTROLS

Hold down motor head switch P2 (Green Label) until motor jogs twice.
 ✓ All remote controls are deleted.

FACTORY RESET

Hold down motor head switch P2 (Green Label) until motor jogs 3 times.
 ✓ Motor restored to default settings.